## Creative Telescoping



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- We want a recurrence for the sum $S(n)=\sum_{k} f(n, k)$.
- Such a recurrence is obtained from a k-free recurrence for $f(n, k)$.
- More precisely, we construct an annihilating operator for $f(n, k)$ of the form

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P\left(n, S_{n}\right)-\Delta_{k} Q\left(n, k, \Delta_{k}, S_{n}\right)
$$

where

- P is nonzero and free of $\mathrm{k}, \mathrm{S}_{\mathrm{k}}, \Delta_{\mathrm{k}}$.
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- P is nonzero and free of $\mathrm{k}, \mathrm{S}_{\mathrm{k}}, \Delta_{\mathrm{k}}$.
- Q may be zero and may involve any variables or operators.
- Then $P\left(n, S_{n}\right)$ is an annihilating operator for $S(n)$.

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"Telescoper"

## $\downarrow$ <br> $P\left(n, S_{n}\right)-\Delta_{k} Q\left(n, k, \Delta_{k}, S_{n}\right)$ <br>  <br> "Certificate"

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- A hypergeometric term $f(n, k)$ is said to telescope (w.r.t. k) if there is a hypergeometric term $\mathrm{g}(\mathrm{n}, \mathrm{k})$ such that

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- The application of a telescoper turns $f(n, k)$ into a telescoping term. (Hence the name.)
- If we only have P, it is not obvious whether P.f telescopes, i.e., whether $P$ is really a telescoper.
- If we have both $P$ and $Q$, then checking $\left(P-\Delta_{k} Q\right) \cdot f \stackrel{?}{=} 0$ is easy. Thus $Q$ certifies that $P$ is a telescoper.

Example. $\sum_{k}\binom{n}{k}^{2}=\binom{2 n}{n}$

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\left((n+1) S_{n}-(4 n+2)\right) \cdot\binom{n}{k}^{2}=\Delta_{k} \cdot \frac{k^{2}(2 k-3 n-3)}{(n+1)^{2}}\binom{n+1}{k}^{2}
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It follows that $(n+1) S_{n}-(4 n+2)$ is an annihilator for $\sum_{k}\binom{n}{k}^{2}$.
The operator $\frac{k^{2}(2 k-3 n-3)}{(n+1)^{2}} S_{n}$ is a certificate for the telescoper.

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This recurrence together with the initial values $W_{0}=\frac{\pi}{2}$ and $W_{1}=1$ determines the whole sequence.

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is a telescoper for $\sin (x)^{n}$.
It maps this function to one that can be explicitly integrated.

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- $\sum_{n=0}^{N}\left(2\binom{2 n}{n} x^{n}-(1-4 x)\binom{2 n}{n}\left(x^{n}\right)^{\prime}\right)=(N+1)\binom{2 N+2}{N+1} x^{N+1}$

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Therefore:

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2 S(x)-(1-4 x) S^{\prime}(x)=\lim _{N \rightarrow \infty}(N+1)\binom{2 N+2}{N+1} x^{N+1}=0
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This differential equation together with the initial value $S(0)=1$ implies the claimed identity.

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- $\int\left(4(1-t) t \frac{\partial^{2}}{\partial t^{2}} f+4(1-2 t) \frac{\partial}{\partial t} f-f\right) d x=-x \sqrt{\frac{1-x^{2}}{\left(1-t x^{2}\right)^{3}}}$

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This differential equation together with the initial values $\mathrm{K}(0)=\frac{\pi}{2}$, $K^{\prime}(0)=\frac{\pi}{8}$ uniquely describes $K(t)$.

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NEW YORK TIMES BESTSELLER
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In the present segment, let's focus on the differential case, and rational functions.

Task.

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- Given: a rational function $f \in C(x, y)$
- Find: operators $P\left(x, D_{x}\right) \neq 0$ and $Q\left(x, y, D_{x}, D_{y}\right)$ such that

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## Equivalently:

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2 the denominator den( $h$ ) of $h$ is square free
$3 \operatorname{deg}_{x} \operatorname{num}(h)<\operatorname{deg}_{x} \operatorname{den}(h)$.
$f$ is integrable in $C(y)$ if and only if $h=0$.

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\begin{aligned}
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& D_{t} \cdot f
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Idea: find a $\mathrm{C}(x)$-linear relation among $h_{0}, h_{1}, h_{2}, \ldots$

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$$
f=D_{y} \cdot 0
$$

$$
+\frac{1}{1+x+y+x y^{3}}
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f & =D_{y} \cdot 0 & & +\frac{1}{1+x+y+x y^{3}} \\
D_{x} \cdot f & =D_{y} \cdot \frac{3 x y^{2}+9 x y+2 y+2}{x(27 x+4)\left(x y^{3}+y+1\right)} & & +\frac{3(y-3)}{(27 x+4)\left(x y^{3}+y+1\right)}
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f & =D_{y} \cdot 0 & & +\frac{1}{1+x+y+x y^{3}} \\
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D_{x}^{2} \cdot f & =D_{y} \cdot \frac{-1622^{3} y^{5}+\cdots-8 y^{2}-16 y-8}{x^{2}(27 x+4)^{2}\left(x y^{3}+y+1\right)^{2}} & +\frac{6(54 x-27 x y-y-1)}{x(27 x+4)^{2}\left(x y^{3}+y+1\right)}
\end{array}
$$

Example. $f=\frac{1}{x y^{3}+y+1}$.

$$
\begin{aligned}
& \frac{1}{1+x+y+x y^{3}} \\
& \frac{3(y-3)}{(27 x+4)\left(x y^{3}+y+1\right)} \\
& \frac{6(54 x-27 x y-y-1)}{x(27 x+4)^{2}\left(x y^{3}+y+1\right)}
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Example. $f=\frac{1}{x y^{3}+y+1}$.

$$
\begin{aligned}
& 6 \frac{1}{1+x+y+x y^{3}} \\
& +2(27 x+1) \frac{3(y-3)}{(27 x+4)\left(x y^{3}+y+1\right)} \\
& +x(27 x+4) \frac{6(57 x-27 x y-y-1)}{x(27 x+4)^{2}\left(x y^{3}+y+1\right)}
\end{aligned}
$$

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\begin{gathered}
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+x(27 x+4) \frac{6(54 x-27 x y-y-1)}{x(27 x+4)^{2}\left(x y^{3}+y+1\right)}=0
\end{gathered}
$$

Therefore,

$$
\begin{aligned}
& \left(6+2(27 x+1) D_{x}+x(27 x+4) D_{x}^{2}\right) \cdot f \\
& =D_{y} \cdot \frac{2\left(3 x^{2} y^{6}+3 x y^{6}-21 x y^{4}-21 x y^{3}-y^{4}-y^{3}+3 y^{2}+6 y+3\right)}{\left(x y^{3}+y+1\right)^{3}}+\mathbf{0}
\end{aligned}
$$

Reduction-based creative telescoping for rational functions
INPUT: $\mathrm{f} \in \mathrm{C}(\mathrm{x}, \mathrm{y})$
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3 if there are $c_{0}, \ldots, c_{r} \in C(x)$, not all zero, such that

$$
c_{0} h_{0}+\cdots+c_{r} h_{r}=0
$$

then return $c_{0}+c_{1} D_{x}+\cdots+c_{r} D_{x}^{r}$

## Reduction-based creative telescoping for rational functions

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then return $c_{0}+c_{1} D_{x}+\cdots+c_{r} D_{x}^{r}$
Exercise. In step 2, we can use $D_{x} \cdot h_{r-1}$ instead of $D_{x}^{r} \cdot f$. Why is this better?

Theorem.

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What happens if we differentiate it a few times?

$$
\begin{aligned}
f & =\frac{p}{q} \\
D_{x} \cdot f & =\frac{p^{\prime} q-p q^{\prime}}{q^{2}}
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\begin{aligned}
& f=\frac{p}{q} \\
& D_{x} \cdot f=\frac{p^{\prime} q-p q^{\prime}}{q^{2}} \\
& D_{x}^{2} \cdot f=\frac{}{q^{3}} \\
& \vdots \\
& D_{x}^{r} \cdot f=\frac{}{q^{r+1}}
\end{aligned}
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$$
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& \\
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$$
\begin{aligned}
\mathrm{f} & =\frac{\mathrm{p}}{\mathrm{q}} \quad \leftarrow \operatorname{deg}_{y}=\operatorname{deg}_{y} p \\
\mathrm{D}_{x} \cdot \mathrm{f} & =\frac{\mathrm{p}^{\prime} \mathrm{q}-\mathrm{pq}^{\prime}}{q^{2}} \leftarrow \operatorname{deg}_{y} \leq \operatorname{deg}_{y} q+\operatorname{deg}_{y} p \\
\mathrm{D}_{x}^{2} \cdot \mathrm{f} & =\frac{}{q^{3}} \\
\vdots & \\
D_{x}^{r} \cdot \mathrm{f} & =\frac{q^{r+1}}{}
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& D_{x} \cdot f=\frac{p^{\prime} q-\mathrm{pq}^{\prime}}{q^{2}} \quad \leftarrow \operatorname{deg}_{y} \leq \operatorname{deg}_{y} q+\operatorname{deg}_{y} p \\
& D_{x}^{2} \cdot f=\frac{\leftarrow \operatorname{qeg}_{y} \leq 2 \operatorname{deg}_{y} q+\operatorname{deg}_{y} p}{} \\
& \vdots \\
& \mathrm{D}_{x}^{r} \cdot f= \\
& \leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p
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$$

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What happens if we differentiate it a few times?

$$
\begin{aligned}
& f=\frac{p q^{r}}{q} q^{r} \\
& \leftarrow \operatorname{deg}_{y}=r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p \\
& D_{x} \cdot f=\frac{p^{\prime} q-p q^{\prime}}{q^{2}} \leftarrow \operatorname{deg}_{y} \leq \operatorname{deg}_{y} q+\operatorname{deg}_{y} p \\
& D_{x}^{2} \cdot f=\frac{\leftarrow \operatorname{deg}_{y} \leq 2 \operatorname{deg}_{y} q+\operatorname{deg}_{y} p}{q^{3}} \\
& \vdots \\
& D_{x}^{r} \cdot f= \\
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\begin{aligned}
& f=\frac{p}{q} q^{r} q^{r} \leftarrow \operatorname{deg}_{y}=r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p \\
& D_{x} \cdot f=\frac{\left(p^{\prime} q-p q^{\prime}\right) q^{r-1} \leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p}{q^{2} q^{r-1}} \\
& D_{x}^{2} \cdot f=\frac{q^{r-2} \leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p}{q^{3} q^{r-2}}{ }^{\vdots} \\
& \begin{array}{ll}
D_{x}^{r} \cdot f & = \\
\leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p
\end{array}
\end{aligned}
$$

## Another approach.

Consider again a rational function $f(x, y)=\frac{p(x, y)}{q(x, y)} \in C(x, y)$.
For every $a_{0}, a_{1}, \ldots, a_{r} \in C(x)$ (free of $y$ ), we have

$$
\left(a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}\right) \cdot f=\frac{\square}{q^{r+1}} \leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q
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$$

For $b_{0}, \ldots, b_{s} \in C(x)$ (also free of $y$ ), consider the rational function

$$
g=\frac{b_{0}+b_{1} y+\cdots+b_{s} y^{s}}{q^{r}}
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$$
g=\frac{b_{0}+b_{1} y+\cdots+b_{s} y^{s}}{q^{r}}
$$

Then

$$
D_{y} \cdot g=\frac{q^{r+1}}{\square} \leftarrow \operatorname{deg}_{y} \leq \operatorname{deg}_{y} q+s-1
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$$
\begin{array}{r}
\left.\left(a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}\right) \cdot f=\frac{\square q^{r+1}}{\leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q} \begin{array}{r}
+\operatorname{deg}_{y} p
\end{array}\right)
\end{array}
$$

For $b_{0}, \ldots, b_{s} \in C(x)$ (also free of $y$ ), consider the rational function

$$
g=\frac{b_{0}+b_{1} y+\cdots+b_{s} y^{s}}{q^{r}}
$$

Then, with $s=(r-1) \operatorname{deg}_{y} q+\operatorname{deg}_{y} p+1$,

$$
D_{y} \cdot g=\frac{\square}{q^{r+1}} \leftarrow \operatorname{deg}_{y} \leq r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p
$$

For undetermined $a_{0}, \ldots, a_{r}$ and $b_{0}, \ldots, b_{s}$, enforce

$$
\left(a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}\right) \cdot f \stackrel{!}{=} D_{y} g
$$

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Comparing coefficients with respect to $y$ leads to a linear system with

- $(r+1)+(s+1)$ variables
- $1+r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p$ equations

For undetermined $a_{0}, \ldots, a_{r}$ and $b_{0}, \ldots, b_{s}$, enforce


Comparing coefficients with respect to $y$ leads to a linear system with

- $(r+1)+\left((r-1) \operatorname{deg}_{y} q+\operatorname{deg}_{y} p+2\right)$ variables
- $1+r \operatorname{deg}_{y} q+\operatorname{deg}_{y} p$ equations

For undetermined $a_{0}, \ldots, a_{r}$ and $b_{0}, \ldots, b_{s}$, enforce


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It will have a nontrivial solution as soon as $r \geq \operatorname{deg}_{y} q-1$.

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It will have a nontrivial solution as soon as $r \geq \operatorname{deg}_{y} q-1$.
Exercise. Does every nonzero solution give rise to a nonzero telescoper?

Example. $f=\frac{1}{x y^{3}+y+1}$

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$$
\begin{aligned}
& \left(a_{0}+a_{1} D_{x}+a_{2} D_{x}^{2}\right) \cdot f \\
& =\frac{\left(a_{0} x^{2}-a_{1} x+2 a_{2}\right) y^{6}+\left(2 a_{0} x-a_{1}\right) y^{4}+\left(2 a_{0} x-a_{1}\right) y^{3}+a_{0} y^{2}+2 a_{0} y+a_{0}}{\left(x y^{3}+y+1\right)^{3}}
\end{aligned}
$$

Example. $f=\frac{1}{x y^{3}+y+1}$

$$
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\end{aligned}
$$

The $y$-derivative of $g=\frac{b_{0}+b_{1} y+b_{2} y^{2}+b_{3} y^{3}+b_{4} y^{4}}{\left(x y^{3}+y+1\right)^{2}}$ is
$\frac{-2 b_{4} x y^{6}-3 b_{3} x y^{5}+\left(2 b_{4}-4 b_{2} x\right) y^{4}+\left(b_{3}-5 b_{1} x+4 b_{4}\right) y^{3}+\left(3 b_{3}-6 b_{0} x\right) y^{2}+\left(2 b_{2}-b_{1}\right) y-2 b_{0}+b_{1}}{\left(x y^{3}+y+1\right)^{3}}$

Example. $f=\frac{1}{x y^{3}+y+1}$

$$
\begin{array}{r}
\left(a_{0} x^{2}-a_{1} x+2 a_{2}+2 b_{4} x\right) y^{6} \\
+3 b_{3} x y^{5} \\
+\left(2 a_{0} x-a_{1}+4 b_{2} x-2 b_{4}\right) y^{4} \\
+\left(2 a_{0} x-a_{1}+5 b_{1} x-b_{3}-4 b_{4}\right) y^{3} \\
+\left(a_{0}+6 b_{0} x-3 b_{3}\right) y^{2} \\
+\left(2 a_{0}+b_{1}-2 b_{2}\right) y \\
+a_{0}+2 b_{0}-b_{1}=0
\end{array}
$$

Example. $f=\frac{1}{x y^{3}+y+1}$

$$
\begin{aligned}
\left(a_{0} x^{2}-a_{1} x+2 a_{2}+2 b_{4} x\right) & =0 \\
+3 b_{3} x & =0 \\
+\left(2 a_{0} x-a_{1}+4 b_{2} x-2 b_{4}\right) & =0 \\
+\left(2 a_{0} x-a_{1}+5 b_{1} x-b_{3}-4 b_{4}\right) & =0 \\
+\left(a_{0}+6 b_{0} x-3 b_{3}\right) & =0 \\
+\left(2 a_{0}+b_{1}-2 b_{2}\right) & =0 \\
+a_{0}+2 b_{0}-b_{1} & =0
\end{aligned}
$$

Example. $f=\frac{1}{x y^{3}+y+1}$

$$
\left(\begin{array}{cccccccc}
x^{2} & -x & 2 & 0 & 0 & 0 & 0 & 2 \chi \\
0 & 0 & 0 & 0 & 0 & 0 & 3 x & 0 \\
2 x & -1 & 0 & 0 & 0 & 4 x & 0 & -2 \\
2 x & -1 & 0 & 0 & 5 x & 0 & -1 & -4 \\
1 & 0 & 0 & 6 x & 0 & 0 & -3 & 0 \\
2 & 0 & 0 & 0 & 1 & -2 & 0 & 0 \\
1 & 0 & 0 & 2 & -1 & 0 & 0 & 0
\end{array}\right)\left(\begin{array}{l}
a_{0} \\
a_{1} \\
a_{2} \\
b_{0} \\
b_{1} \\
b_{2} \\
b_{3} \\
b_{4}
\end{array}\right)=0
$$

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$$
\left.\left(\begin{array}{l}
a_{0} \\
a_{1} \\
a_{2} \\
b_{0} \\
b_{1} \\
b_{2} \\
b_{3} \\
b_{4}
\end{array}\right) \in\left(\begin{array}{c}
6 x \\
2 x(27 x+1) \\
x^{2}(27 x+4) \\
-1 \\
2(3 x-1) \\
9 x-1 \\
0 \\
-3 x(x+1)
\end{array}\right)\right\rangle
$$

Example. $f=\frac{1}{x y^{3}+y+1}$

$$
\begin{aligned}
& \left(6 x+2 x(27 x+1) D_{x}+x^{2}(27 x+4) D_{x}^{2}\right) \cdot f \\
& =D_{y} \cdot \frac{-1+2(3 x-1) y+(9 x-1) y^{2}-3 x(x+1) y^{4}}{\left(x y^{3}+y+1\right)^{2}}
\end{aligned}
$$

The Apagodu-Zeilberger Algorithm
INPUT: $f \in C(x, y)$
OUTPUT: a telescoper and a certificate for $f$

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3 make an ansatz $P=a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}$
4 make an ansatz $g=\left(b_{0}+b_{1} y+\cdots+b_{s} y^{s}\right) / \operatorname{den}(f)^{r}$

## The Apagodu-Zeilberger Algorithm

INPUT: $\mathrm{f} \in \mathrm{C}(\mathrm{x}, \mathrm{y})$
OUTPUT: a telescoper and a certificate for f
$1 \quad \mathrm{r}=\operatorname{deg}_{\mathrm{y}} \operatorname{den}(\mathrm{f})$
$2 \quad s=(r-1) \operatorname{deg}_{y} q+\operatorname{deg}_{y} p+1$
3 make an ansatz $P=a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}$
4 make an ansatz $g=\left(b_{0}+b_{1} y+\cdots+b_{s} y^{s}\right) / \operatorname{den}(f)^{r}$
5 equate the $y$-coefficients of $\operatorname{den}(f)^{r+1}\left(P \cdot f-D_{y} \cdot g\right)$ to zero and solve the resulting linear system

## The Apagodu-Zeilberger Algorithm

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$1 \quad \mathrm{r}=\operatorname{deg}_{\mathrm{y}} \operatorname{den}(\mathrm{f})$
$2 \quad s=(r-1) \operatorname{deg}_{y} q+\operatorname{deg}_{y} p+1$
3 make an ansatz $P=a_{0}+a_{1} D_{x}+\cdots+a_{r} D_{x}^{r}$
4 make an ansatz $g=\left(b_{0}+b_{1} y+\cdots+b_{s} y^{s}\right) / \operatorname{den}(f)^{r}$
5 equate the $y$-coefficients of $\operatorname{den}(f)^{r+1}\left(P \cdot f-D_{y} \cdot g\right)$ to zero and solve the resulting linear system
6 for a solution vector $\left(a_{0}, \ldots, a_{r}, b_{0}, \ldots, b_{s}\right)$ with at least one nonzero $a_{i}$, return $P$ and $g$

Summary.

Summary.

$$
P\left(n, S_{n}\right)-\Delta_{k} Q\left(n, y, \Delta_{k}, S_{n}\right)
$$

Summary.

$$
\underbrace{P\left(n, S_{n}\right)}_{\text {telescoper (nonzero!) }}-\Delta_{k} \underbrace{Q\left(n, y, \Delta_{k}, S_{n}\right)}_{\text {certificate }}
$$

Summary.

$$
\underbrace{\mathrm{P}\left(x, \mathrm{D}_{\chi}\right)}_{\text {telescoper (nonzero!) }}-\Delta_{\mathrm{k}} \underbrace{\mathrm{Q}\left(x, y, \Delta_{k}, \mathrm{D}_{x}\right)}_{\text {certificate }}
$$

Summary.

$$
\underbrace{P\left(n, S_{n}\right)}_{\text {telescoper (nonzero!) }}-D_{\text {certificate }} \underbrace{Q\left(n, y, D_{y}, S_{n}\right)}_{y}
$$

Summary.

$$
\underbrace{\mathrm{P}\left(x, \mathrm{D}_{x}\right)}_{\text {telescoper (nonzero!) }}-\mathrm{D}_{y} \underbrace{\mathrm{Q}\left(x, y, \mathrm{D}_{y}, \mathrm{D}_{x}\right)}_{\text {certificate }}
$$

Summary.

$$
\underbrace{\mathrm{P}\left(x, \mathrm{D}_{x}\right)}_{\text {telescoper (nonzero! })}-\mathrm{D}_{y} \underbrace{\mathrm{Q}\left(x, y, \mathrm{D}_{y}, \mathrm{D}_{x}\right)}_{\text {certificate }}
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- Creative telescoping is the search for a telescoper (with or without a corresponding certificate).

Summary.

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- Creative telescoping is the search for a telescoper (with or without a corresponding certificate).
- Sister Celine's algorithm is a creative telescoping algorithm for hypergeometric terms.


## Summary.

$$
\underbrace{\mathrm{P}\left(x, \mathrm{D}_{x}\right)}_{\text {telescoper (nonzero!) }}-\mathrm{D}_{y} \underbrace{\mathrm{Q}\left(x, y, \mathrm{D}_{y}, \mathrm{D}_{x}\right)}_{\text {certificate }}
$$

- Creative telescoping is the search for a telescoper (with or without a corresponding certificate).
- Sister Celine's algorithm is a creative telescoping algorithm for hypergeometric terms.
- For rational functions in the differential case, we have two creative telescoping algorithms:

Reduction-based telescoping | Apagodu-Zeilberger algorithm |
| :--- | :--- |

Hermite reduction

+ small linear system
large linear system

